

PHYS2006

2011/2012
Sem 1 Exam

(A1)
$$\underline{R} = \frac{1}{M} \sum_{i=1}^N m_i \underline{r}_i ; \quad M = \sum_{i=1}^N m_i \quad \left. \right\} [2]$$

where m_i are the masses and \underline{r}_i the position for the N particles. Thus

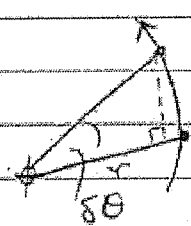
$$\underline{R} = \frac{1}{M} \sum_{i=1}^N m_i \dot{\underline{r}}_i = \frac{1}{M} \underline{P} \quad \text{or} \quad \boxed{\underline{P} = M \underline{R}} \quad \left. \right\} [2]$$

since the individual momenta are $m_i \dot{\underline{r}}_i$

(A2) For a force \underline{F} applied at a point \underline{r}
the torque $\underline{\tau} = \underline{r} \times \underline{F}$ ① force subtended constant

$$\underline{\tau} = \frac{d}{dt} \underline{L} \quad \text{where } \underline{L} \text{ is angular momentum.} \quad \left. \right\} [2]$$


If the force is central then $\underline{F} \propto \underline{r}$, so $\underline{\tau} = 0 \Rightarrow \underline{L} = \text{constant w.r.t. time i.e. conserved.} \quad \left. \right\} [2]$

(A3)  In time δt , the particle's radius sweeps out an area $\delta A = \frac{1}{2} r^2 \delta \theta$ therefore $\frac{dA}{dt} = \frac{1}{2} r^2 \dot{\theta}$ ① given $\dot{\theta}$ is the angular velocity

but $L = M r (r \dot{\theta}) = M r^2 \dot{\theta}$ is a constant, so $\frac{dA}{dt}$ is a constant implying that equal

① areas are swept out in equal times. NB \Rightarrow Kepler's 2nd law

(A4) Looking down from the N pole, the ball is projected tangentially when viewed from an inertial frame. Gravitational force is central so angular momentum is conserved. ①

 Therefore as ball falls, its angular velocity increases ①

(A4) continued -

with the consequence that the ball gets slightly ahead of the tower as it falls. [2]

(AS) The Coriolis force is the term

$$-2m \omega \times \underline{x}$$

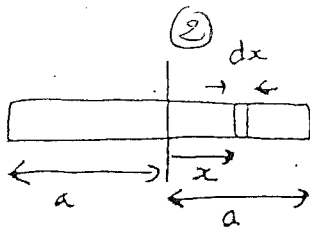
that appears in Newton's equation of motion ^{for the particle} when considered in the rotating frame of the Earth. Here ω is the angular velocity of the Earth, and m and \underline{x} are the mass and (apparent) velocity of the particle. [2]

It thus supplies a force at right angles to the direction of motion. Foucault's pendulum is simply a pendulum attached to a stationary frame, typically very large so that it can swing unaided for a long time. Then it is found ^(clockwise from above) that the plane in which it swings precesses at an angular velocity of $\omega \sin \lambda$, λ being the latitude, as may be derived from the Coriolis force

For substantially correct [2] B

(B1)

(a)

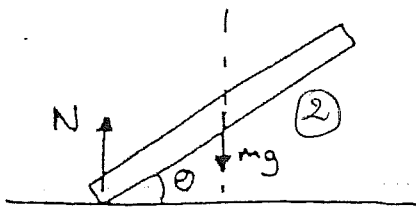


Let $\rho = \frac{\text{mass}}{\text{length}}$ per unit length.

$$dI = \rho dx x^2 \Rightarrow I = \int_{-a}^a \rho x^2 dx = \frac{2\rho a^3}{3} = \frac{1}{3} ma^2 \quad [6]$$

(b)

CM of rod descends in a vertical line, one end remains in contact with table, but slides across it. Apply conservation of energy \rightarrow



$$mga \begin{matrix} \swarrow \text{initial pe} \\ \uparrow \text{pe} \end{matrix} = mga \sin \theta + \frac{1}{2} \cdot \frac{1}{3} ma^2 \dot{\theta}^2 + \frac{1}{2} ma^2 \cos^2 \theta \dot{\theta}^2 \begin{matrix} \uparrow \text{rot. ke about CM} \\ \uparrow \text{linear ke of cm.} \end{matrix} \quad [4]$$

$$\left(\frac{1}{6} ma^2 + \frac{1}{2} ma^2 \cos^2 \theta \right) \dot{\theta}^2 = mga (1 - \sin \theta) \quad [2]$$

when $\theta = 0$ fixed:

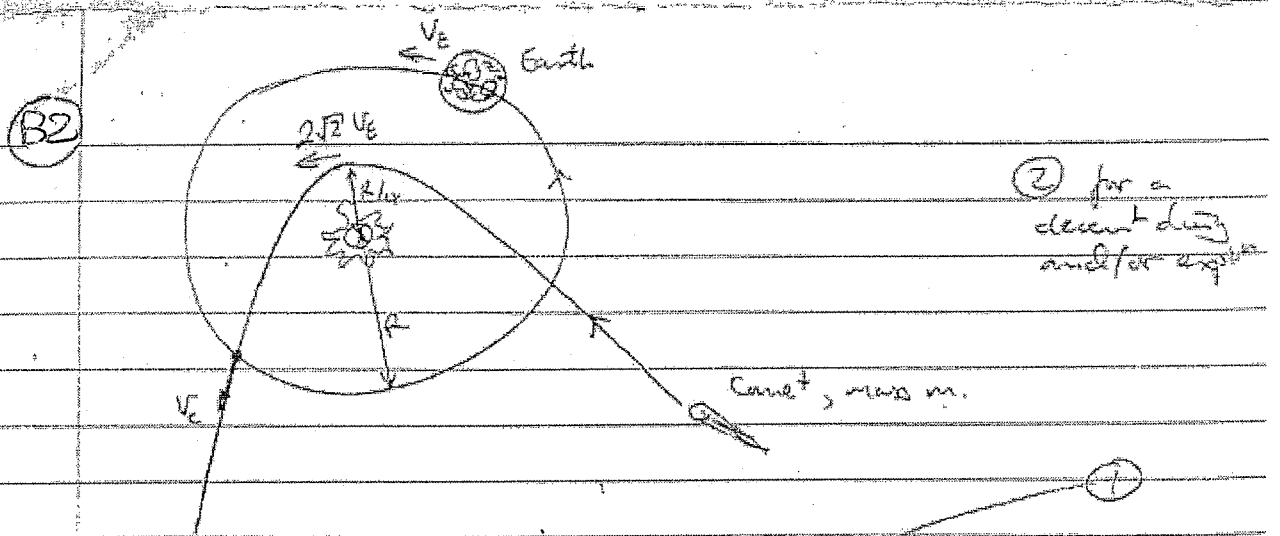
$$\dot{\theta}^2_{\theta=0} = \frac{ga}{\frac{1}{6}a^2 + \frac{1}{2}a^2} = \frac{3g}{2a} \quad [2]$$

$$|\dot{\theta}|_{\theta=0} = \sqrt{\frac{3g}{2a}} \quad [4]$$

First parts of (b): ① CM of rod descends vertically

② Reaction force N does no work, since it is displaced perpendicular to its direction [1]

③ Energy is conserved. [1]



At closest approach comet's velocity is \perp to its position displacement from the sun therefore its angular momentum

$$L = m \left(\frac{R}{4} \right) (2\sqrt{2} v_E) = \frac{1}{\sqrt{2}} m R v_E \quad (*) \quad [5]$$

Its total energy $E = \frac{1}{2} m (2\sqrt{2} v_E)^2 - \frac{GMm}{R/4} = 4m v_E^2 - 4 \frac{GMm}{R}$

When it crosses Earth's orbit with speed v_c , $E = \frac{1}{2} m v_c^2 - \frac{GMm}{R}$ (conserved energy) (2)

But Earth's motion $\frac{v_E^2}{R} = \frac{GM}{R^2}$ (circular motion) (3)

(1) & (2) $\Rightarrow 4 v_E^2 - 3 \frac{GM}{R} = \frac{1}{2} v_c^2$

(3) $\Rightarrow = v_E^2 \Rightarrow v_c = \sqrt{2} v_E \quad [7]$

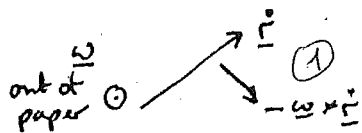
From (*) we have that the tangential component of velocity when comet crosses Earth's orbit so $v_t = v_E / \sqrt{2}$

we have $\cos \theta = \frac{1}{2} \Rightarrow \theta = 60^\circ$ i.e. angle at crossing $\theta = 60^\circ$

B3

□ Two inertial force terms in eqn. motion.

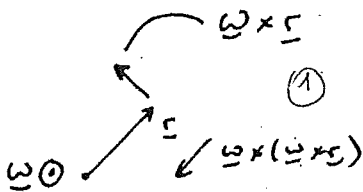
(i) Coriolis term $-2m\omega \times \dot{\underline{r}}$ [2]



Direction of cross product shows that ② bug feels a force perp to its velocity, directed towards the right.

magnitude: $2m\omega u$ [3]

(ii) centrifugal term. $-m\omega \times (\omega \times \underline{r})$ [2]



$\omega \times (\omega \times \underline{r})$ points radially inwards, ② so $-\omega \times (\omega \times \underline{r})$ is radially outwards

magnitude $m\omega^2 r$ [3]

-normal "centrifugal force" term.

□ For bug not to slip: consider horizontal part of eqn. of motion. [2]

$\ddot{\underline{r}} = 0$ in the rotating frame so, [2]

$\underline{F} = 2m\omega \times \dot{\underline{r}} + m\omega \times (\omega \times \underline{r})$

o we clearly want $|\underline{F}| < \mu mg$ for no-slip (using vertical part of eqn. motion) [2]

o Coriolis and centrifugal terms are orthogonal, so

$\mu^2 g^2 < 4\omega^2 u^2 + \omega^4 r^2$ [2]

So it can get to

$r = \frac{[\mu^2 g^2 - 4\omega^2 u^2]^{1/2}}{\omega^2}$

[2] before it slips

(B2) continued -

Comet can escape if it has ^{zero or +ve} energy at ∞ distance from sun (= its kinetic energy there) but energy will be

$$E = 4mV_e^2 - \frac{4GMm}{R} \quad (\text{by } \textcircled{1})$$

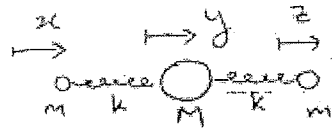
$$= 0 \quad (\text{by } \textcircled{2})$$

\therefore Comet has just enough energy to escape $\textcircled{1}$ [3]

(B1) Normal mode: each part of the system oscillates with same frequency, but in general different amplitude and phase.

[1]B

[1]B



[1]

$$MII \Rightarrow m \ddot{x} = -k(x-y) \quad [1]$$

$$M \ddot{y} = k(x-y) - k(y-z) \quad [1]$$

$$m \ddot{z} = k(y-z) \quad [1]$$

Thus

$$\begin{pmatrix} \ddot{x} \\ \ddot{y} \\ \ddot{z} \end{pmatrix} = \begin{pmatrix} -k/m & k/m & 0 \\ k/m & -2k/M & k/M \\ 0 & k/m & -k/m \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad [1]$$

(1^B for matrix, 1 for det)

Look for normal mode: $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} A \\ B \\ C \end{pmatrix} e^{i\omega t}$ [1]B

Require $\begin{vmatrix} \omega^2 - k/m & k/m & 0 \\ k/m & \omega^2 - 2k/M & k/M \\ 0 & k/m & \omega^2 - k/m \end{vmatrix} = 0$ (1^B for det, 1 for det) [2]

$$\Rightarrow (\omega^2 - k/m) \{ (\omega^2 - 2k/M)(\omega^2 - k/m) - k^2/Mm \} - k^2/mM (\omega^2 - k/m) = 0 \quad [1]$$

$$\Rightarrow \omega^2 (\omega^2 - k/m) (\omega^2 - k/m - 2k/M) = 0 \quad [1]$$

* Also for $\omega = 0$: find $A=B=C \Rightarrow$ mode of uniform translation of whole system at const. velocity [1]*

for intuitive derivation

$\omega = \sqrt{k/m}$: $\begin{pmatrix} 0 & k/m & 0 \\ k/m & k/m - 2k/M & k/M \\ 0 & k/m & 0 \end{pmatrix} \begin{pmatrix} A \\ B \\ C \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ $B=0$ $A=-C$ [1]*

Central mass at rest. Outer masses oscillate out of phase.

$\omega = \left(\frac{k}{m} + \frac{2k}{M} \right)^{1/2}$: $\begin{pmatrix} 2k/M & k/m & 0 \\ k/m & k/m & k/M \\ 0 & k/m & 2k/M \end{pmatrix} \begin{pmatrix} A \\ B \\ C \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ $A=C$ $B = -\frac{2m}{M} C$ [1]

Outer two masses oscillate in phase; inner mass out of phase with outer masses, different amplitude. [1]

