

Phys 3007 - 2015

Theories of matter, space and Time

Model answers

A1

(i) $L(q_1, q_n, \dot{q}_1, \dot{q}_n, t)$ (Lagrangian)

q_k ignorable, or cyclic, if L does not depend on q_k [1]

in which case $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_k} \right) = \frac{\partial L}{\partial q_k} = 0$

$\Rightarrow p_k = \frac{\partial L}{\partial \dot{q}_k}$ conserved [1]

(ii) Lagrangian for a particle moving in a plane under a central conservative force:

$$L = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} m r^2 \dot{\vartheta}^2 - V(r) \quad [1]$$

L independent of ϑ - ϑ is cyclic \Rightarrow

$$\Rightarrow 0 = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\vartheta}} \right) = \frac{d}{dt} (m r^2 \dot{\vartheta}) \quad [1]$$

$L =$ angular momentum

is conserved

[Variant of example in lectures]

A2]

$\Delta x^\mu \Delta x_\mu$ invariant

$$\Rightarrow c^2 \Delta t_{(2)}^2 - \Delta x_{(2)}^2 = c^2 \Delta t_{(1)}^2 - \Delta x_{(1)}^2 \quad [1]$$

$$\Delta x_{(1)} = 0 \Rightarrow \Delta x_{(2)} = c \sqrt{\Delta t_{(2)}^2 - \Delta t_{(1)}^2}$$

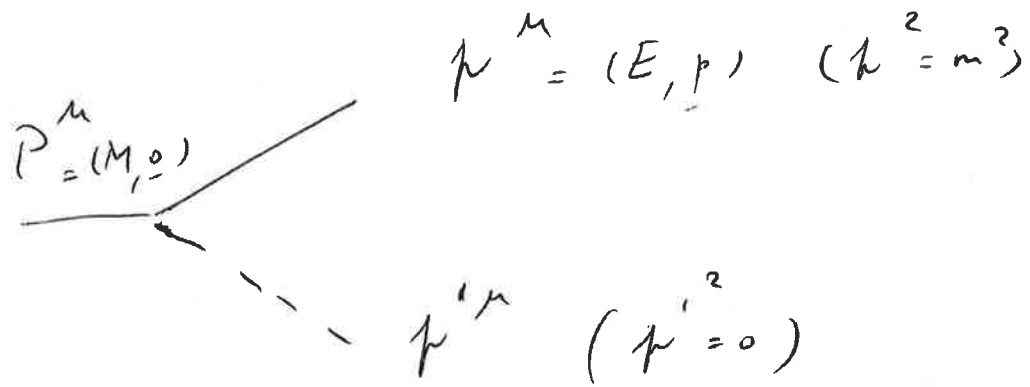
$$= 3 \cdot 10^8 \sqrt{16 - 4} \text{ m}$$

$$\approx 10^9 \text{ m}$$

[1]

[variant of question in problem sheet]

A3]



Four-momentum conservation implies

$$P - k = k' \Rightarrow (P - k)^2 = k'^2 \Rightarrow M^2 + m^2 - 2mE = 0 \quad [1]$$

$$\Rightarrow E = \frac{M^2 + m^2}{2M}$$

Therefore

$$T = E - m = \frac{M^2 + m^2}{2M} - m = \frac{(M - m)^2}{2M} \quad [1]$$

A6)

~~Electromagnetism~~
[Lecture notes]

a) Four-gradient $\partial^\mu = (\frac{\partial}{\partial t}, -\underline{\nabla})$ [1]

Four-potential $A^\mu = (\varphi, \underline{A})$ [1]

Four-current $J^\mu = (\rho, \underline{J})$ [1]

Field strength tensor $F^{\mu\nu} = \partial^\mu A^\nu - \partial^\nu A^\mu$ [1]

b) The two terms on the lhs of the given equations are respectively $\partial_\mu \partial^\mu A^\nu$ and $-\partial^\nu \partial_\mu A^\mu$, while the rhs is $\mu_0 J^\nu$ ($c=1 \Rightarrow \mu_0 \epsilon_0 = 1$):

$$\partial_\mu \partial^\mu A^\nu - \partial^\nu \partial_\mu A^\mu = \mu_0 J^\nu \quad [1]$$

By exchanging order of derivatives in the 2nd term on the lhs we have:

$$\partial_\mu (\underbrace{\partial^\mu A^\nu - \partial^\nu A^\mu}_{F^{\mu\nu}}) = \mu_0 J^\nu \quad [1]$$

i.e.

$$\partial_\mu F^{\mu\nu} = \mu_0 J^\nu$$

AS)

Multiply Klein-Gordon equation by ϕ^*

$$\phi^* \partial_\mu \partial^\mu \phi + m^2 \phi^* \phi = 0 \quad [1]$$

and take complex conjugate equation multiplied by ϕ

$$\phi \partial_\mu \partial^\mu \phi^* + m^2 \phi \phi^* = 0 \quad [1]$$

Subtract the two equations, mass terms cancel, and we get

$$\phi^* \partial_\mu \partial^\mu \phi - \phi \partial_\mu \partial^\mu \phi^* = 0 \quad [1]$$

that is,

$$\partial_\mu (\phi^* \partial^\mu \phi - \phi \partial^\mu \phi^*) = (\partial_\mu \phi^*) \partial^\mu \phi + (\partial_\mu \phi) \partial^\mu \phi^* = 0$$

Cancelling the last two terms,

$$\partial_\mu (\underbrace{\phi^* \partial^\mu \phi - \phi \partial^\mu \phi^*}_{-i j^\mu}) = 0 \quad [1]$$

$$\Rightarrow j^\mu = i (\phi^* \partial^\mu \phi - \phi \partial^\mu \phi^*), \quad \partial_\mu j^\mu = 0 \quad [1]$$

B1)

a)

$$\text{upper mass: } L_1 = \frac{1}{2} m_1 l^2 \dot{\theta}^2 - m_1 g l (1 - \cos \theta) \quad [2]$$

$$\text{lower mass: } L_2 = \frac{1}{2} m_2 l^2 (\dot{\theta}^2 + \dot{\phi}^2 + 2 \cos(\phi - \theta) \dot{\theta} \dot{\phi}) \\ - m_2 g l (1 - \cos \theta) - m_2 g l (1 - \cos \phi) \quad [2]$$

$$L = L_1 + L_2 \quad [2]$$

b) $m_1 = m_2 = m$. For small oscillations,

$$L = \frac{1}{2} m l^2 (2 \dot{\theta}^2 + \dot{\phi}^2 + 2 \dot{\theta} \dot{\phi}) - m g l \left(\theta^2 + \frac{\phi^2}{2} \right) \quad [2]$$

Euler Lagrange equations:

$$\begin{cases} 2 m l^2 \ddot{\theta} + m l^2 \ddot{\phi} = - 2 m g l \theta & [1] \\ m l^2 \ddot{\phi} + m l^2 \ddot{\theta} = - m g l \phi & [1] \end{cases}$$

i.e.

$$\begin{cases} 2 \ddot{\theta} + \ddot{\phi} = - \frac{2g}{l} \theta \\ \ddot{\phi} + \ddot{\theta} = - \frac{g}{l} \phi \end{cases}$$

Separating second derivatives terms,

$$\ddot{\theta} = - \frac{g}{l} (2\theta - \phi) \quad [1]$$

$$\ddot{\phi} = - \frac{2g}{l} (\phi - \theta) \quad [1]$$

$$c) \quad \frac{d^2}{dt^2} \begin{pmatrix} \theta \\ \phi \end{pmatrix} = - \underbrace{\begin{pmatrix} 2g/l & -g/l \\ -2g/l & 2g/l \end{pmatrix}}_{\theta} \begin{pmatrix} \theta \\ \phi \end{pmatrix}$$

Normal frequencies!

$$\det(\mathcal{D} - \omega^2 \mathbb{1}) = 0 \Rightarrow \det \begin{pmatrix} 2g/l - \omega^2 & -g/l \\ -2g/l & 2g/l - \omega^2 \end{pmatrix} = 0 \quad [2]$$

$$\text{i.e., } \left(\frac{2g}{l} - \omega^2\right)^2 - 2\left(\frac{g}{l}\right)^2 = 0$$

$$\text{So } \omega_{\pm}^2 = \frac{2g}{l} \pm \sqrt{2} \frac{g}{l} = \frac{g}{l} (2 \pm \sqrt{2}) \quad [2]$$

$$\frac{\omega_+}{\omega_-} = \sqrt{\frac{2 + \sqrt{2}}{2 - \sqrt{2}}} = \frac{2 + \sqrt{2}}{\sqrt{2}} = \sqrt{2} + 1 \quad [1]$$

$$d) \quad \text{For the two normal modes, } \begin{pmatrix} \theta \\ \phi \end{pmatrix} = \begin{pmatrix} \theta_{\pm} \\ \Phi_{\pm} \end{pmatrix} e^{i\omega_{\pm} t}$$

$$\Rightarrow \begin{pmatrix} -\omega_{\pm}^2 + 2g/l & -g/l \\ -2g/l & -\omega_{\pm}^2 + 2g/l \end{pmatrix} \begin{pmatrix} \theta_{\pm} \\ \Phi_{\pm} \end{pmatrix} = 0 \quad [1]$$

$$\text{So } (-\omega_{\pm}^2 + 2g/l) \theta_{\pm} - g/l \Phi_{\pm} = 0$$

$$\text{that is, } \mp \sqrt{2} \frac{g}{l} \theta_{\pm} - g/l \Phi_{\pm} = 0 \quad [1]$$

$$\Rightarrow \Phi_{\pm} = \mp \sqrt{2} \theta_{\pm} \quad [1]$$

B2

a) 4-momentum conservation $p' = p + k - k'$ [2]

$$\Rightarrow m^2 = p'^2 = (p + k - k')^2 = m^2 + 2m(\omega - \omega') + 2\omega\omega'(1 - \cos\theta)$$
 [2]

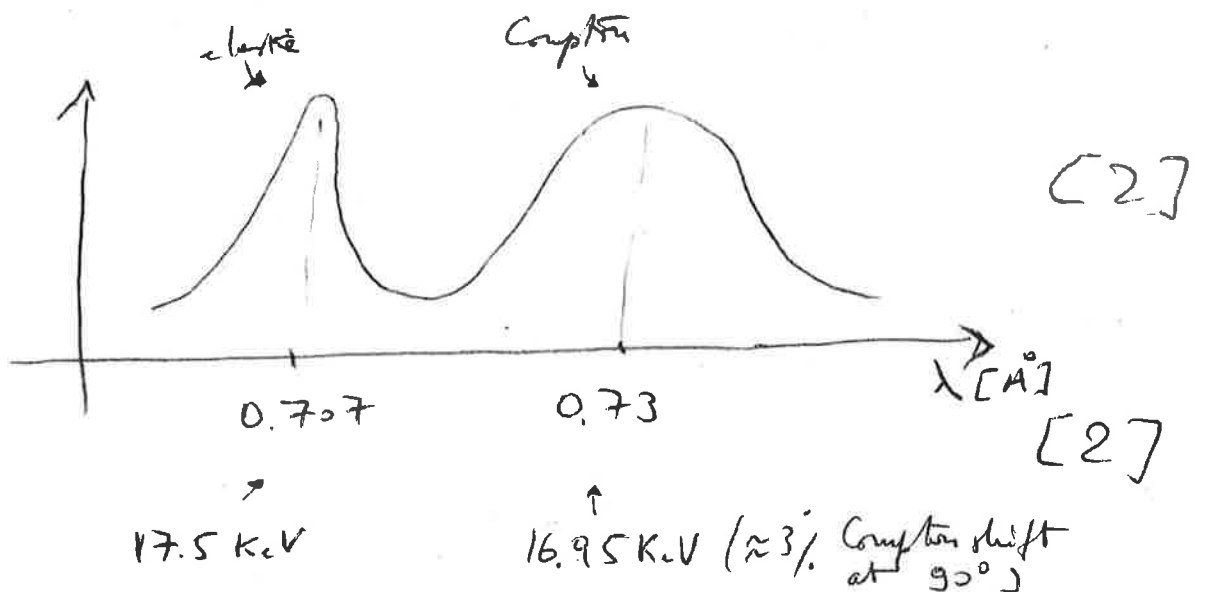
i.e.

$$2m\omega = 2\omega' [m + \omega(1 - \cos\theta)]$$

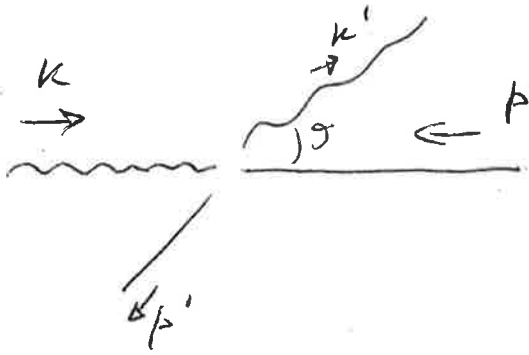
So $\omega' = \frac{\omega}{1 + \frac{\omega}{m}(1 - \cos\theta)}$ [2]

b) elastic scattering by nuclei and tightly bound electrons [1]

Compton scattering off nearly free electrons [1]



e)



Applying 4-momentum conservation now gives

$$m^2 = p'^2 = (p + k - k')^2 = m^2 + \underbrace{2p \cdot (k - k')}_{2E_2(E - E') - 2\sqrt{E_2^2 - m_2^2} * (-E + E' \cos \theta)} - 2EE'(1 - \cos \theta) \quad [1]$$

$$\Rightarrow 2EE'(1 - \cos \theta) = 2E_2(E - E') + 2\sqrt{E_2^2 - m_2^2}(E - E' \cos \theta) \quad [1]$$

that is,

$$E' [2E(1 - \cos \theta) + 2E_2 + 2\sqrt{E_2^2 - m_2^2} \cos \theta] = 2E_2 E + 2\sqrt{E_2^2 - m_2^2} E$$

$$\text{So } E' = \frac{E(E_2 + \sqrt{E_2^2 - m_2^2})}{\sqrt{E_2^2 - m_2^2} \cos \theta + E_2 + E(1 - \cos \theta)} \quad [1]$$

Maximum E' for minimum of denominator $\Rightarrow \theta = \pi$ [1]

Expanding $\sqrt{E_2^2 - m_2^2} \approx E_2 - \frac{m_2^2}{2E_2}$ gives [1]

$$E'_{\text{max}} \approx \frac{2EE_2}{2E + E_2 - E_2 + \frac{m_2^2}{2E_2}} = \frac{E}{E/E_2 + \frac{m_2^2}{4E_2^2}} \quad [1]$$

$$\lambda = 514 \Rightarrow E = 2.4 \text{ eV}$$

$$\text{Thus } E'_{\text{max}} \approx \frac{2.4}{\frac{2.4}{27 \cdot 10^9} + \frac{0.511^2 \cdot 10^{12}}{4 \cdot 27^2 \cdot 10^{18}}} \text{ eV} \approx 13.5 \text{ GeV} \Rightarrow 5 \cdot 10^9 \text{ increase} \quad [2]$$

B3

$$L = \frac{1}{2} m \dot{x}^2 - e \varphi + e \underline{x} \cdot \underline{A}$$

a) $\frac{d}{dt} \frac{\partial L}{\partial \dot{x}_j} - \frac{\partial L}{\partial x_j} = 0 \Rightarrow$

$$\nabla_j \equiv \frac{\partial}{\partial x_j}$$

$$\Rightarrow \frac{d}{dt} (m \dot{x}_j + e A_j) + e \nabla_j \varphi - e \nabla_j (\dot{x} \cdot \underline{A}) = 0 \quad [1]$$

Using $\frac{d}{dt} A_j = \frac{\partial}{\partial t} A_j + \dot{x} \cdot \nabla A_j \Rightarrow$ [1]

$$\Rightarrow m \ddot{x}_j + e \frac{\partial A_j}{\partial t} + e \dot{x} \cdot \nabla A_j + e \nabla_j \varphi - e \nabla_j (\dot{x} \cdot \underline{A}) = 0 \quad [1]$$

\swarrow
 $-e E_j$
 $(\underline{E} = -\nabla \varphi - \frac{\partial \underline{A}}{\partial t})$



$-e (\dot{x} \wedge \underline{B})_j$ [2]
 because
 $\dot{x} \wedge (\nabla \wedge \underline{A})_j = \nabla_j (\dot{x} \cdot \underline{A}) - (\dot{x} \cdot \nabla) A_j$

$(\underline{B} = \nabla \wedge \underline{A})$

Thus

$$m \ddot{x}_j = e [E_j + (\dot{x} \wedge \underline{B})_j]$$

[2]

$$m \ddot{x} = e [\underline{E} + \dot{x} \wedge \underline{B}]$$

b) $p_j = \frac{\partial L}{\partial \dot{x}_j} = m \dot{x}_j + e A_j$ [1]

\uparrow
 depends on
 vector potential [1]

$$c) \quad H = \sum_j p_j \dot{x}_j - L$$

$$= \underline{p} \cdot \underline{\dot{x}} - \frac{1}{2} m \underline{\dot{x}}^2 + e\varphi - e \underline{\dot{x}} \cdot \underline{A} \quad [1]$$

using $\underline{p} = m \underline{\dot{x}} + e \underline{A} \Rightarrow \underline{\dot{x}} = \frac{1}{m} (\underline{p} - e \underline{A}) \quad [1]$

$$= \frac{1}{m} \underline{p} \cdot (\underline{p} - e \underline{A}) - \frac{1}{2m^2} m (\underline{p} - e \underline{A})^2 + e\varphi - \frac{e}{m} (\underline{p} - e \underline{A}) \cdot \underline{A} \quad [2]$$

$\underbrace{\hspace{10em}}_{\frac{1}{m} (\underline{p} - e \underline{A})^2}$

$$= \frac{1}{2m} (\underline{p} - e \underline{A})^2 + e\varphi \quad [2]$$

d) $L \rightarrow L + \frac{df}{dt}$, $\frac{df}{dt} = \frac{\partial f}{\partial t} + \underline{\dot{x}} \cdot \underline{\nabla} f$ has no effect on equations of motion

[1]

It is equivalent to gauge transformations of the potentials:

[1]

$$L + \frac{df}{dt} = \frac{1}{2} m \dot{x}^2 - e\varphi + \frac{df}{dt} + e \underline{\dot{x}} \cdot \underline{A} + \underline{\dot{x}} \cdot \underline{\nabla} f$$

$$= \frac{1}{2} m \dot{x}^2 - e \underbrace{\left[\varphi - \frac{\partial}{\partial t} \left(\frac{f}{e} \right) \right]}_{\varphi'} + e \underline{\dot{x}} \cdot \underbrace{\left[\underline{A} + \underline{\nabla} \left(\frac{f}{e} \right) \right]}_{\underline{A}'} \quad [2]$$

gauge-transformed potentials

$$\varphi' = \varphi - \partial \lambda / \partial t, \quad \underline{A}' = \underline{A} + \underline{\nabla} \lambda$$

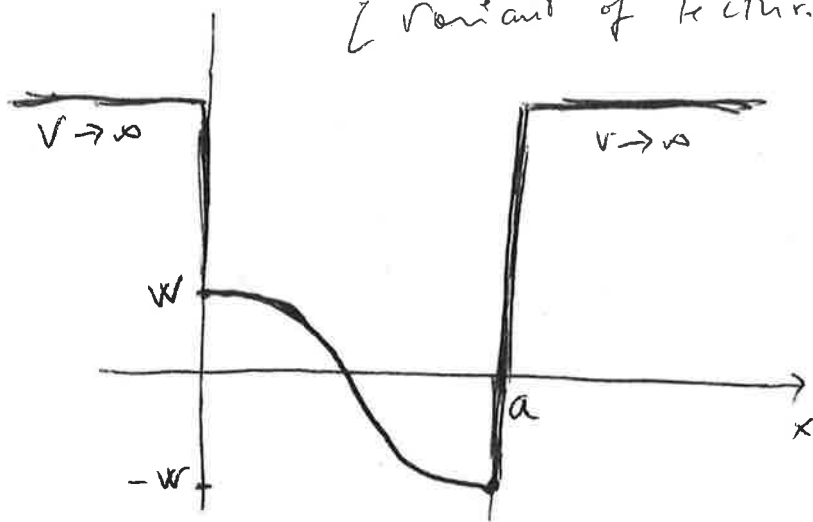
with $\lambda = f/e$

[1]

[variant of lecture example]

B4)

a)



[2]

b) The stationary states of the unperturbed system

have well-defined parity about $x = \frac{a}{2}$ [1]

while the perturbation has odd parity [1]

Therefore $\delta E_n^{(1)} = \int u_n^* H_1 u_n dx = 0$ for all n . [2]

c)
$$\delta \psi_1^{(1)} = \sum_m u_m \frac{1}{E_1^{(0)} - E_m^{(0)}} \int u_m^* H_1 u_1 dx$$
 [1]

Note that $H_1 u_1 = W \cos \frac{\pi x}{a} \sqrt{\frac{2}{a}} \sin \frac{\pi x}{a} =$

$$= \frac{W}{2} \sqrt{\frac{2}{a}} \sin \frac{2\pi x}{a} = \frac{W}{2} u_2$$
 [1]

Thus $\int u_m^* H_1 u_1 = \frac{W}{2} \delta_{m2}$ [1]

$$\Rightarrow \delta \psi_1^{(1)} = \frac{W}{2} \frac{1}{E_1^{(0)} - E_2^{(0)}} u_2 = - \frac{W}{6 E_1^{(0)}} u_2$$
 [2]

$$\psi_1^{(1)} = u_1 - \frac{W}{6 E_1^{(0)}} u_2$$

The correction tends to cancel the zeroth-order [1]

Contribution for $x < \frac{a}{2}$ and add to it for $x > \frac{a}{2}$ [1]

\Rightarrow particle is more localized around the minimum of the potential. [1]

Perturbation theory gives a suitable approximation provided the coefficient in $\delta\psi_1^{(1)}$ is small, i.e. $W \ll 6E_1^{(0)}$. [2]

$$d) \quad \delta E_n^{(2)} = \sum_m \frac{|\int \psi_m^* H_1 \psi_n|^2}{E_n - E_m} \quad [1]$$

$$n=1: \text{ recall from c) } \int \psi_m^* H_1 \psi_1 = \frac{W}{2} \delta_{m2}$$

$$\Rightarrow \delta E_1^{(2)} = \left(\frac{W}{2}\right)^2 \left(\frac{1}{-3E_1^{(0)}}\right) = -\frac{W^2}{12E_1^{(0)}} \quad [1]$$

$$n=2: \text{ note that } H_1 \psi_2 = W \sqrt{\frac{2}{a}} \sin \frac{2\pi x}{a} \Leftrightarrow \frac{\pi x}{a} =$$

$$= \frac{W}{2} \sqrt{\frac{2}{a}} \left(\sin \frac{3\pi x}{a} + \sin \frac{\pi x}{a} \right)$$

$$= \frac{W}{2} (\psi_3 + \psi_1) \quad [1]$$

$$\Rightarrow \int \psi_m^* H_1 \psi_2 = \frac{W}{2} (\delta_{m3} + \delta_{m1})$$

$$\text{Then } \delta E_2^{(2)} = \left(\frac{W}{2}\right)^2 \left[\frac{1}{E_2^{(0)} - E_3^{(0)}} + \frac{1}{E_2^{(0)} - E_1^{(0)}} \right] = \frac{W^2}{4E_1^{(0)}} \left(-\frac{1}{5} + \frac{1}{3} \right) \quad [1]$$

$$= \frac{W^2}{30E_1^{(0)}}$$